Raspberry Pi as a Satellite Tracker

Controlling the SatNOGS rotator Jonathan Brandenburg, 01/16/2016

Install gpredict

- "sudo apt-get update"
- "sudo apt-get install gpredict"
- Start "gpredict"



Configure gpredict Totator

- "Edit", "Preferences"
- Select the "Interfaces" module, select the "Rotators" tab.
- Create a network-based rotator on "localhost", port 4533
 - no physical reason maximum azimuth could not be > 360 or maximum elevation could not be > 90.

000	X GPREDICT Preferences :: Interfaces		
22	Radios Rotators		
General	Config Name Host Port Min Az Max Az Min El Max El Azimuth Type SatNOGS localhost 4533 0° 360° 0° 90° 0° → 180° → 360°		
Modules			
Interfaces	Name Sations Host localhost Port 4533		
Predict	Az type $0^{\circ} \rightarrow 180^{\circ} \rightarrow 360^{\circ}$ Min Az 0° Max Az 360° Min El 0° Max El 90° $\stackrel{\bullet}{=}$ $\stackrel{\bullet}{=}$ Max El 90°		
📥 Add New 📝 Edit 🗑 Delete			
	Cancel Cancel		

Install the Rotator Control Software

- "sudo apt-get update"
- "sudo apt-get install libhamlib-utils"
- Start the rotator control daemon with "sudo rotctld -m 202 -r /dev/ttyACMO -s 19200 -T 127.0.0.1"
 - -m 202 specifies a rotator compatible with "Easycommll"
 - /dev/ttyACMO is the serial port of the Arduino. It may be different at times.



Activate Tracking in gpredict

- Click the down-arrow in the "radar" window, select "Antenna Control"
- Click "Engage" beside the rotator device
- Select the desired target.

Click "Track"		X Gpredict Rotator Control: Amateur	
	Azimuth 3 5 3 3 1 ° * * * * * *	Elevation 3 1 0 6 ° • • • • • •	KF5IDY_QTH N 20:04 20:01
	Target GO-32 ▼ Tr	Settings	19:58
	Az: 354.47° El: 36.01° ΔT: 05:24	Cycle: 1000 + msec Tolerance: 5.00 + deg	19:55 19:52 S